

WalkVLM : Aid Visually Impaired People Walking by Vision Language Model

Supplementary Material

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|-----|---|----------|
| 001 | Contents | |
| 002 | A Walking Awareness Dataset | 1 |
| 003 | A.1. Data Regional Distribution | 1 |
| 004 | A.2. Dataset Category Definition | 1 |
| 005 | A.3. Annotation Process | 1 |
| 006 | A.4. Detection Model | 1 |
| 007 | A.5. Sample Visualization | 2 |
| 008 | A.6. Data Analysis | 3 |
| 009 | A.7. Benchmark Data Splits | 3 |
| 010 | B Model & Details | 4 |
| 011 | B.1. All Prompts Used in Paper | 4 |
| 012 | B.2. Evaluation of Temporal Redundancy F1-Score | 6 |
| 013 | C Experiment | 6 |
| 014 | C.1. Visualization of Hierarchical Reasoning . . . | 6 |
| 015 | C.2. Visual Comparison of Different Models . . . | 6 |
| 016 | C.3. Comparison of Video Streaming Inference . | 6 |
| 017 | D Discussion | 7 |
| 018 | E Societal Impact | 8 |
| 019 | A. Walking Awareness Dataset | |
| 020 | A.1. Data Regional Distribution | |
| 021 | Table A1 shows the data distribution and corresponding du- | |
| 022 | ration in the WAD dataset. The WAD dataset covers ten | |
| 023 | cities and contains a wide range of data sources. Figure A1 | |
| 024 | illustrates the relevant regional distribution. As illustrated, | |
| 025 | our dataset is spread across Asia and Europe, showing a | |
| 026 | relatively balanced distribution between different regions. | |
| 027 | Furthermore, the sampling across different regions is rela- | |
| 028 | tively uniform, with a large number of samples at various | |
| 029 | locations to avoid bias, which has good generalization char- | |
| 030 | acteristics. | |
| 031 | A.2. Dataset Category Definition | |
| 032 | As shown in Table A2, WAD dataset contains multiple pre- | |
| 033 | defined data categories. For weather conditions, we have | |
| 034 | selected the most common types, avoiding scenarios such | |
| 035 | as rainy or snowy days that make visually impaired people | |
| 036 | (VIPs) difficult to go outside. For location types, we have | |
| 037 | selected the types where VIPs are likely to appear, avoid- | |
| 038 | ing rare locations. For the traffic flow rating, we instructed | |
| 039 | annotators to count the number of people in each video seg- | |
| 040 | ment and used this count as the basis for classification. For | |

| City | Country | Hours |
|--------------|-------------|-------|
| Amsterdam | Netherlands | 1:21h |
| Bangkok | Thailand | 2:55h |
| Chiang Mai | Thailand | 1:07h |
| Istanbul | Turkey | 1:08h |
| Kuala Lumpur | Malaysia | 1:12h |
| Singapore | Singapore | 1:36h |
| Stockholm | Sweden | 1:06h |
| Venice | Italy | 1:50h |
| Zurich | Switzerland | 1:05h |
| Beijing | China | 2:33h |

Table A1. The source region and duration of the WAD dataset. Refer to Fig. A1 for visualization results.

scene summarization, during annotation, we required anno- 041
tators to summarize static attributes such as road conditions, 042
pedestrian flow, and vehicle flow, providing a comprehensive 043
description of the current environment. Currently, the gran- 044
ularity of our dataset is still relatively coarse. In the future, 045
we will continue to refine different fine-grained categories 046
and gradually expand the size of the dataset. 047

A.3. Annotation Process 048

We use the page shown in Figure A2 to request annotators 049
to make marks. For static tags, we have provided relevant 050
options for the annotators. For scene summary, we require 051
annotators to describe aspects such as the scene, road con- 052
ditions, pedestrian flow, and vehicle flow. For reminder and 053
QA, we require annotators to expand on different situations, 054
as described in Section 3.2 of the main paper. Since descrip- 055
tive tags carry a temporal dimension, we have adopted the 056
annotation method in Table A3 for labeling. After the text 057
categorization is completed, we perform a quality inspection 058
on it and use Llama3.1¹ to normalize the samples that pass 059
the inspection to debias. 060

A.4. Detection Model 061

The Detic model [1] has achieved excellent results on the 062
LVIS benchmark [2] in open-world detection tasks by train- 063
ing the detector classifier on image classification data. In 064
view of the model’s good generalization ability, we use it to 065
perform preliminary target extraction on the WAD dataset. 066
Figure A3 presents some example of the detection results 067

¹<https://ai.meta.com/blog/meta-llama-3-1/>

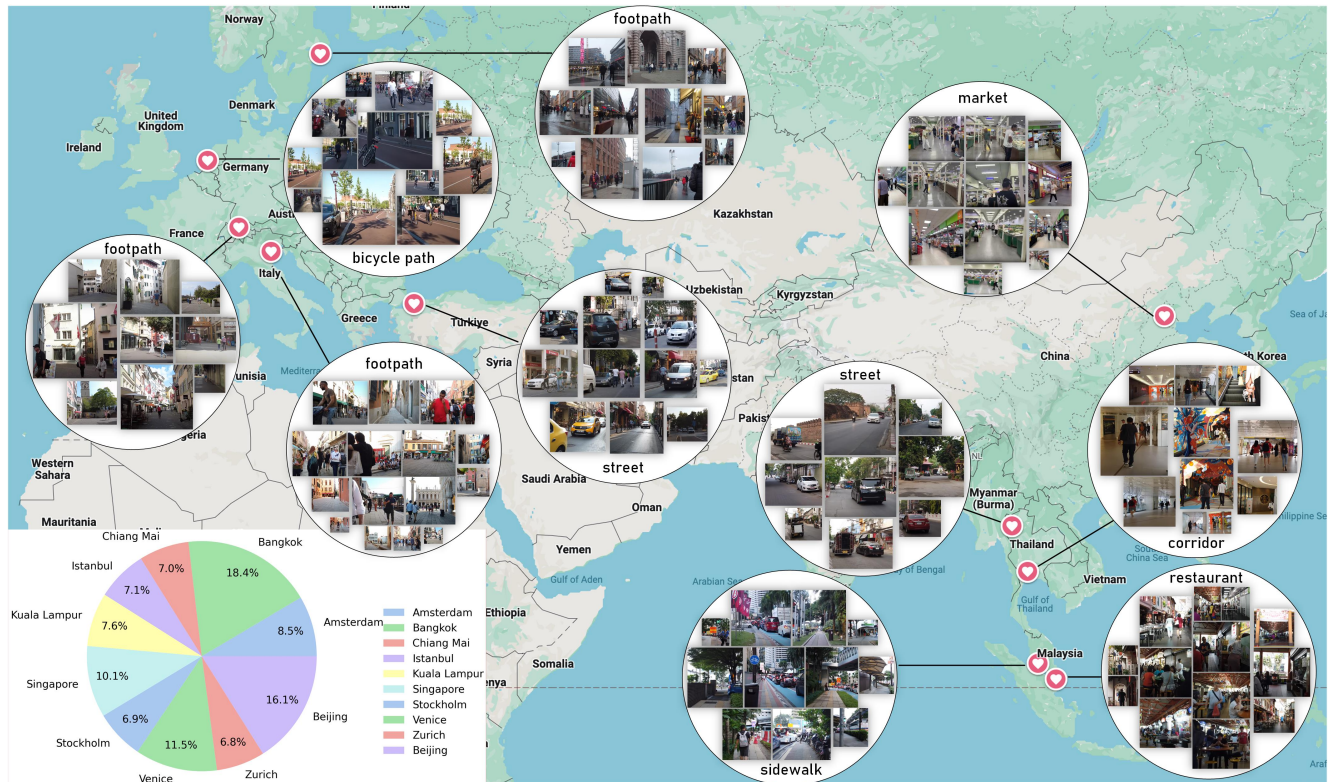


Figure A1. Visualization results of the WAD dataset sorted by region. The WAD dataset has a wide range of sources, and the samples and categories shown are randomly obtained from the dataset. The pie chart in the lower left corner shows the proportion of video length from different regions.

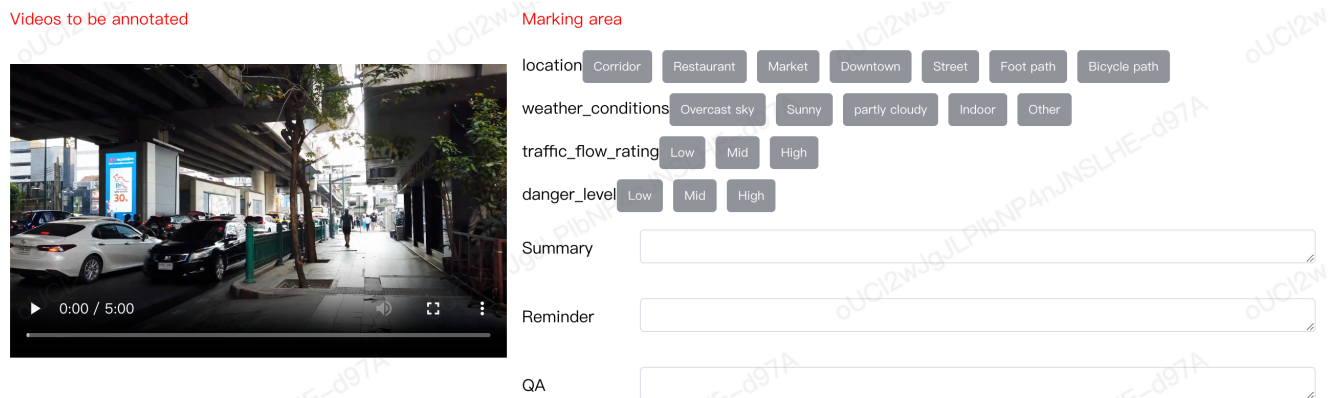


Figure A2. Annotation tool interface. Annotators mark the static attributes of the video in the video, record the time points of reminders and QA, and enter corresponding text descriptions.

068 of the Detic model in the WAD dataset, demonstrating that
 069 the model has a strong ability to extract small and complex
 070 targets. After using the model for detection, we conducted
 071 manual confirmation and deleted some false positive boxes,
 072 thus obtaining the final detection results.

A.5. Sample Visualization

Figure A4 and Figure A5 show more sample visualization results in the WAD dataset. Our dataset has wide coverage, diverse types, and possesses ideal reminder attributes to train VLM to have guiding capabilities in blind walking tasks.

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| Tag Type | Category | Note |
|---------------------|-----------------|---|
| Weather Conditions | Sunny | - |
| | Night | Not make fine-grained distinctions |
| | Overcast | - |
| | Cloudy | - |
| | Indoor | Not make fine-grained distinctions |
| | Other | Severe weather conditions such as rain and fog for walking |
| Location Type | Busy Street | Open-air commercial streets |
| | Road | Roads where vehicles can travel normally |
| | Restaurant | Food stalls gathered together, inside large canteens |
| | Pedestrian Path | Walking paths in parks and other places for healthy walking |
| | Corridor | Indoor walking paths |
| | Bicycle Lane | Bicycle roads with bicycle signs |
| | Shopping Mall | Large shopping supermarkets |
| Other | Niche scenarios | |
| Traffic Flow Rating | Low | Fewer than 2 people appear in the sliced video |
| | Mid | Between 2 and 10 people appear in the sliced video |
| | High | More than 10 people appear in the sliced video |
| Danger Level | Low | The road is clear, the pedestrian flow is low, and no dangers within 15 steps |
| | Mid | Other scenarios that do not belong to low or high |
| | High | Potential collision factors, such as narrow roads, bumpy roads, vehicle warnings |
| Scene Description | - | Detailed description of the current environment, level of danger, and pedestrian flow |
| QA | - | The three types of inquiries mentioned in the paper and concise responses |
| Reminder | - | Brief walking directions to provide to the user based on the current scenario |

Table A2. The interpretation of label categories contained in the WAD dataset.

Figure A3. The detection results provided in the WAD dataset, which were pre-detected by the Detic model [1], and then manually reviewed to ensure the correctness of the results. See [here](#) for more detection samples.

078 A.6. Data Analysis

079 Figure A7 shows the distribution of the top 100 categories
080 contained in the WAD dataset, while Table A4 shows all
081 the categories included. Figure A6 presents a word cloud
082 distribution with annotated descriptions, where the most
083 frequently used words include *oclock*, *pedestrian*, *direction*.
084 We have counted the word count distribution in different

annotated texts in Figure A8. For reminder and QA scenarios, 085
the data contained in WAD is shorter in length, while for 086
summary scenario descriptions are more detailed. 087

A.7. Benchmark Data Splits 088

To ensure the diversity of test data, we adopted a category- 089
based combined clustering method. Through this method, 090
we carefully selected a certain number of samples from the 091



Weather condition: Sunny **Area type:** Street **Danger level:** Low **Traffic flow rating:** Mid

Summary: The current road is flat. There is a parked vehicle five steps to the left. There is a huge building on the right. There are trees at twelve o'clock. There is a huge building behind the trees. The current weather is sunny and there are many pedestrians on the current road. There is a yellow billboard above the position ten steps to the left.

Q: How long to the intersection?

A: Go straight about twenty steps to reach, there are a row of iron piers at 11 o'clock direction, and there are two iron pillars on the ground right in front.



Weather condition: Night **Area type:** Street **Danger level:** Mid **Traffic flow rating:** Mid

Summary: In the evening on a street, there are trees and street lamps on the right. The sky is dim and the street lamps are on. About 20 steps at one o'clock, there are several passersby. About 30 steps in front, there are several passersby and a car. There are some shops on both sides of the road. About 30 steps at one o'clock, there is a building with colored lights. The road surface is flat but slippery.

Q: How to go?

A: Go towards 11 o'clock, avoiding the street lights and trees in the middle of the walkway.



Weather condition: Sunny **Area type:** Pedestrian Path **Danger level:** Low **Traffic flow rating:** Low

Summary: On a walking path, there are rows of cars parked in front and on the right. On the silver-grey car on the right, there is a black-and-white cow cat squatting. About 15 steps ahead, there is a pedestrian in white. On the left, there is a row of metal railings, and inside the railings are residential buildings. The road is narrow, there are few pedestrians, and no vehicles passing.

Q: Current road situation.

A: The current road is a small road with cars parked on both sides. There are few pedestrians on the road. Now, walk to the left side of the road, which is relatively narrow. Be careful to avoid the cars parked on the right side and pay attention to safety.

Figure A4. Visual examples of QA samples in WAD dataset. See [here](#) for dynamic samples.

092 clustering results to form our test set. Ultimately, we selected
093 1007 reminders and 134 QA pairs as our testset. Furthermore,
094 we conducted a thorough analysis of the distribution of the
095 test set to confirm that they are accurate and that the same
096 type of data is represented in the training set.

B. Model & Details

097


B.1. All Prompts Used in Paper

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Table A5 displays all the prompts utilized in this paper under various circumstances such as normalizing annotation

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Weather condition: Sunny **Area type:** Other **Danger level:** Mid **Traffic flow rating:** Mid

Summary: Right side is glass door, 10 steps away on the right side there is a cart, and there are pedestrians ahead.


Reminder: There is a glass wall in front, be careful to avoid it.



Weather condition: Overcast **Area type:** Pedestrian Path **Danger level:** Mid **Traffic flow rating:** Mid

Summary: Walking on a stone bridge. The left side is red, and the right side is paved with stone bricks. There are stone railings on both sides of the bridge. There are many trees below and on both sides of the bridge. There is a pedestrian in a black coat about five steps ahead. The large flow of people is mainly concentrated about fifteen steps ahead. There is no road nearby, and the traffic flow is zero.


Reminder: at 10 o'clock direction, there are pedestrians passing by. please move slowly towards 11 o'clock direction.



Weather condition: Sunny **Area type:** Pedestrian Path **Danger level:** Mid **Traffic flow rating:** Low

Summary: On the sidewalk on the right side of the road, there is a downward step on the left. A yellow car passes on the left side of the road. There is a row of green plants on the right. There is a row of trees at the one o'clock direction. There is a sign at the two o'clock direction. There are cars parked on the roadside at the eleven o'clock direction. The current road is narrow, and there are few pedestrians.

Reminder: At 11 o'clock direction there is a car, at 1 o'clock direction there is a sign, be careful to avoid.



Weather condition: Sunny **Area type:** Pedestrian Path **Danger level:** High **Traffic flow rating:** Mid

Summary: On a sidewalk, there is a telegraph pole at 10 o'clock, and a billboard in front, about to be hit. At 10 o'clock on the left, two pedestrians are pushing items forward. A takeaway motorcycle is parked on the roadside at 1 o'clock. As the lens moves forward, a couple are walking hand in hand on the sidewalk at 10 o'clock. At 1 o'clock, about five steps away, there is an electric box and a telegraph pole. There is a stall at 11 o'clock. Many cars are parked on the right side of the road waiting to pass. The road is narrow with many roadblocks.

Reminder: At 11 o'clock direction, there are pedestrians passing by. about five steps in front, there are telegraph poles and electric boxes. be careful to avoid.

Figure A5. Visual examples of reminder samples in WAD dataset. See [here](#) for dynamic samples.

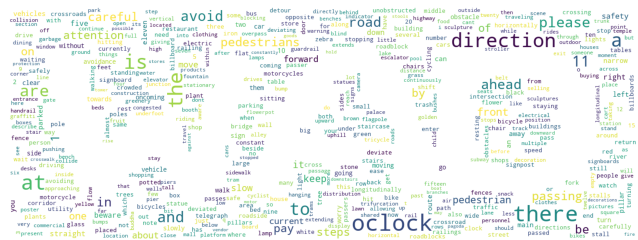


Figure A6. Word cloud distribution of the description in Walking Awareness Dataset.

...
 <2m30s - AE>
almost hit the wall, go forward in the 11 o'clock direction to return to the main route.
 <2m43s - B>
five steps ahead is the fork in the road, go forward in the 10 - o'clock direction to return to the main route.
 ...
 <3m39s - O>
 Q: describe the current scene
 A: at a crossroads with many vehicles, keep still to avoid, there are some obstacles ahead, be careful to avoid
 ...

Table A3. Example of reminder and QA result annotation with a temporal dimension. We required annotators to mark the time when events occurred in the video, the question and reminder categories, as well as concise responses.

101 results, reasoning with VLM, and conducting evaluations.
 102 Normalize the annotation results are crucial for ensuring the
 103 consistency and uniformity of annotation results, and this
 104 prompt are used in the preprocessing stage to correct bias in
 105 the data. For the inference prompt of other models, we input
 106 historical multi-frame images and historical states to enable
 107 it to generate trigger states and reminders for the user. In the
 108 prompt of WalkVLM, we make the model predict different
 109 levels of labels step by step and gradually output the results.
 110 The evaluation prompt based on GPT4 compares different re-
 111 sults with the ground truth to obtain the proportion statistics
 112 of the optimal model.

113 B.2. Evaluation of Temporal Redundancy F1-Score

114 This section systematically evaluates the redundancy of tempo-
 115 ral outputs of different models. Temporal redundancy
 116 refers to the excessive frequency of output information in this
 117 paper. In order to evaluate the temporal redundancy of differ-
 118 ent models, we decompose the test video to ensure that each
 119 sample contains historical N frames and N states, thereby
 120 predicting the trigger state under the current situation. We
 121 collected 834 such samples as a test set. The predicted labels

are divided into three levels, corresponding to the degree
 of danger. When the degree of danger is high, we regard it
 as triggering VLM. By comparing the predicted different
 states with the ground truth, the distribution gap between the
 two sets of data can be calculated, thereby calculating the
 F1-score.

128 C. Experiment

129 C.1. Visualization of Hierarchical Reasoning

130 We have demonstrated the results of hierarchical reasoning
 131 using WalkVLM in Figure A9. WalkVLM can effectively
 132 extract static attributes from video streams and generate a
 133 comprehensive summary of the current scene. After integrat-
 134 ing fragmented attributes, the model produces concise and
 135 informative walking instructions.

136 C.2. Visual Comparison of Different Models

137 Figure A10 and A11 presents a comparison of additional
 138 visualization results between WalkVLM and other models.
 139 Our approach yields more streamlined results, enabling a
 140 superior human-machine interaction experience during blind
 141 walking task.

142 C.3. Comparison of Video Streaming Inference

143 In this section, we deployed WalkVLM and MiniCPM-V2.6
 144 [3] on cloud devices to verify the differences in performance
 145 between the two models in real-world scenarios. The visu-
 146 alization results of the two models on the video stream can
 147 be viewed here, where WalkVLM is capable of generating
 148 less temporal redundancy. As shown in A12, on real-time
 149 video streams, for two models with the same size parameters,
 150 WalkVLM can generate more concise and accurate walking
 151 guidance.

152 However, the current model still has certain **limitations** in
 153 practical applications. **Firstly**, the model has a weak ability
 154 to prioritize events, making it difficult to identify the most
 155 urgent actions that need reminders in the scene. Facing this
 156 issue, our next attempt is to establish an event priority model
 157 that enables the model to propose necessary events and ob-
 158 tain priority results through ranking. **Second**, the model still
 159 has certain misjudgments in obstacle recognition and direc-
 160 tion. Going forward, we will attempt to inject more prior
 161 knowledge about obstacles into the model and try to design
 162 some rule-based methods to verify the output of WalkVLM,
 163 so as to enhance its usability. **Thirdly**, there is still signif-
 164 icant room for improvement in the model's recognition of
 165 fine-grained obstacles. We believe that this can be compen-
 166 sated for by collecting more available data.

167 Although there are the aforementioned shortcomings,
 168 compared to other models, WalkVLM has made a solid
 169 advancement in the blind walking task. We will continue

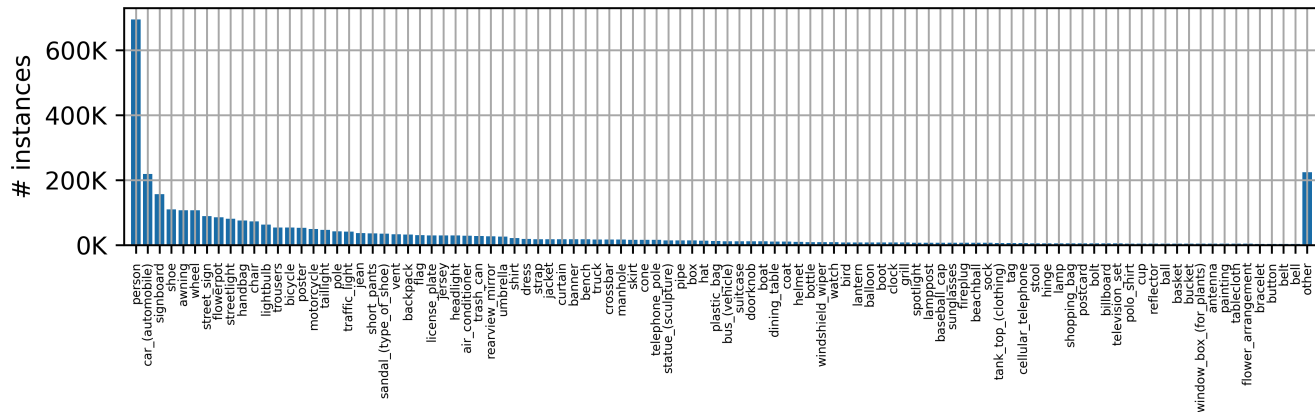


Figure A7. Detect target distribution. For clarity, display the top 100 with the highest frequency of occurrence.

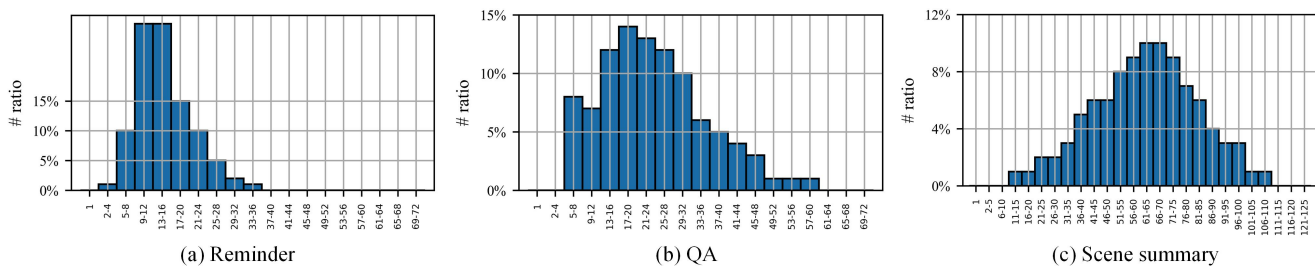


Figure A8. Data length distribution in different text annotation types.

170 to iterate on this model to further enhance its usability in
171 real-world scenarios!

172 D. Discussion

173 In the context of the increasingly popular vision-language
174 model field, it is crucial to explore how to use it to address
175 the daily challenges faced by visually impaired patients. Our
176 work on the WalkVLM model and the walking awareness
177 dataset represents a significant step in this direction, aiming
178 to empower individuals with visual impairments through
179 advanced technological solutions.

180 One of the most rewarding aspects of this research has
181 been the opportunity to apply cutting-edge AI research to
182 a problem that has profound real-world implications. We
183 are deeply committed to leveraging technology to enhance
184 the quality of life for everyone, and our work on WalkVLM
185 exemplifies this mission. By providing a tool that can offer
186 more accurate and context-aware guidance, we hope to
187 make a tangible difference in the lives of blind individuals,
188 enabling them to navigate their environments with greater
189 independence and confidence.

190 However, we also recognize that our current approach
191 has several limitations that need to be addressed to fully
192 realize its potential. One major limitation is the geographical
193 scope of our dataset, which currently covers only Europe
194 and Asia. To develop a truly global solution, we need to

expand our data collection efforts to include a wider range of
regions and environments. This will ensure that our model
can adapt to the diverse conditions and challenges faced by
blind individuals around the world.

Another important consideration is the need for more
real-time capabilities in our model. While WalkVLM offers
significant advancements in understanding and interpreting
walking-related data, achieving rapid inference is essential
for practical applications. Real-time processing allows for
immediate feedback and adjustments, which are critical for
ensuring the safety and effectiveness of assistive technologies.

Additionally, integrating Retrieval-Augmented Generation (RAG) techniques [4, 5] could further enhance the information provided by our model. By combining WalkVLM with RAG, we can incorporate a broader range of perspectives and data sources, leading to more informative and contextually relevant responses. This approach not only improves the accuracy and utility of our model but also fosters a more dynamic and interactive user experience.

In conclusion, while our work on WalkVLM achieves a significant advancement in the field of assistive technologies for the visually impaired, there is still much to be done. By addressing the limitations mentioned above and continuing to innovate, we hope to build on our current achievements and contribute to a future where technology empowers indi-

person, car-(automobile), signboard, shoe, awning, wheel, street-sign, flowerpot, streetlight, handbag, chair, lightbulb, trousers, bicycle, poster, motorcycle, taillight, pole, traffic-light, jean, short-pants, sandal-(type-of-shoe), vent, backpack, flag, license-plate, jersey, headlight, air-conditioner, trash-can, rearview-mirror, umbrella, shirt, dress, strap, jacket, curtain, banner, bench, truck, crossbar, manhole, skirt, cone, telephone-pole, statue-(sculpture), pipe, box, hat, plastic-bag, bus-(vehicle), suitcase, doorknob, boat, dining-table, coat, helmet, bottle, windshield-wiper, watch, bird, lantern, balloon, boot, clock, grill, spotlight, lamppost, baseball-cap, sunglasses, fireplug, beachball, sock, tank-top-(clothing), tag, cellular-telephone, stool, hinge, lamp, shopping-bag, postcard, bolt, billboard, television-set, polo-shirt, cup, reflector, ball, basket, bucket, window-box-(for-plants), antenna, painting, tablecloth, flower-arrangement, bracelet, bunion, belt, bell, baby-buggy, flagpole, ladder, bowl, spectacles, vase, clock-tower, blouse, book, stop-sign, handle, banana, refrigerator, toy, sunhat, beanie, doughnut, necklace, train-(railroad-vehicle), bottle-cap, fan, tarp, vest, crate, orange-(fruit), magazine, apple, skateboard, parking-meter, postbox-(public), necktie, dog, earring, vending-machine, sweatshirt, barrel, lampshade, chandelier, cowboy-hat, minivan, newsstand, choker, hook, dish-antenna, scarf, camera, pizza, mask, drawer, weathervane, figurine, motor-scooter, magnet, pigeon, speaker-(stereo-equipment), cart, cooler-(for-food), blackboard, roller-skate, hot-air-balloon, flip-flop-(sandal), unicycle, headscarf, cabinet, hatbox, mirror, legging-(clothing), candle, saichel, teddy-bear, lanyard, log, glove, pennant, wall-socket, shower-cap, blinker, canister, pottery, robe, gargyle, steering-wheel, newspaper, suspenders, dumpster, water-bottle, easel, kite, cushion, apron, horse, wreath, pew-(church-bench), dispenser, tomato, towel, melon, pumpkin, doormat, fire-extinguisher, sombrero, walking-cane, can, telephone-booth, thermostat, wineglass, heart, bandanna, tambourine, cat, jar, peach, carton, ring, frisbee, pot, carrot, watering-can, surfboard, mailbox-(at-home), headband, buoy, coconut, hose, card, sweater, lemon, remote-control, butterfly, grape, plate, knob, gravestone, knocker-(on-a-door), elephant, globe, mast, paper-plate, raincoat, wristlet, projector, watermelon, tote-bag, pirate-flag, mail-slot, tray, bulletproof-vest, brass-plaque, handcart, table, tricycle, towel-rack, laptop-computer, belt-buckle, fire-alarm, bow-(decorative-ribbons), slipper-(footwear), sink, papaya, sawhorse, briefcase, glass-(drink-container), cake, latch, coat-hanger, step-stool, fish-(food), napkin, pastry, motor, shopping-cart, sofa, silo, doll, toilet, tank-(storage-vessel), cookie, crucifix, oven, bamboo, tassel, hairnet, golfcart, fish, bread, cam, monitor-(computer-equipment) computer-monitor, lion, seashell, microwave-oven, earphone, Christmas-tree, water-jug, wagon-wheel, airplane, locker, broom, calendar, pop-(soda), barrette, mammoth, Rollerblade, avocado, blazer, scoreboard, hippopotamus, birdbath, shield, rubber-band, paper-towel, music-stool, straw-(for-drinking), poncho, neckerchief, pinwheel, houseboat, crutch, green-bean, birthday-card, sunflower, pickup-truck, grocery-bag, wine-bottle, faucet, halter-top, wine-bucket, sandwich, life-buoy, basketball-backboard, bullhorn, aerosol-can, tapestry, toilet-tissue, bathtub, tripod, dogfish, gourd, fireplace, stepladder, orange-juice, edible-corn, oil-lamp, garden-hose, potato, shower-curtain, water-tower, knife, onion, apricot, tennis-racket, piggy-bank, ashtray, puppet, sculpture, pretzel, fedora, brassiere, milk-can, cantaloup, blimp, blanket, guitar, kiwi-fruit, brake-light, armor, shawl, scissors, table-tennis-table, toothbrush, birdcage, lettuce, cylinder, radiator, turban, kimono, birdhouse, slide, envelope, Dixie-cup, Ferris-wheel, microphone, swimsuit, lime, beer-bottle, shaving-cream, fishbowl, ice-skate, camper-(vehicle), hairpin, pillow, underwear, oar, bonnet, chinaware, cymbal, penguin, sausage, strawberry, costume, dishtowel, gull, sword, bagel, spoon, crown, harmonium, duffel-bag, candle-holder, camcorder, horse-buggy, jumpsuit, clothes-hamper, knee-pad, bathrobe, comic-book, beer-can, giant-panda, map, phonograph-record, bell-pepper, toolbox, solar-array, rhinoceros, booklet, cupcake, shower-head, binoculars, monkey, matchbox, hand-towel, deer, pan-(for-cooking), wheel, wheelchair, armoire, camel, goose, hair-dryer, dress-hat, tiger, tennis-ball, place-mat, bridal-gown, ottoman, cornice, mug, pear, sail, boxing-glove, passenger-car-(part-of-a-train), cap-(headwear), horse-carriage, urn, wig, wind-chime, thermos-bottle, fume-hood, crock-pot, bubble-gum, cherry, drum-(musical-instrument), wagon, bed, clarinet, eyepatch, tissue-paper, padlock, cigarette, parasol, baseball-bat, teacup, mandarin-orange, aquarium, bun, bowling-ball, telephone, lemonade, dog-collar, windmill, saltshaker, tartan, zucchini, lab-coat, tinsel, radar, pitcher-(vessel-for-liquid), pug-dog, sheep, coffee-maker, folding-chair, pinecone, visor, octopus-(animal), medicine, cassette, yogurt, saddlebag, wardrobe, basketball, persimmon, tape-(sticky-cloth-or-paper), nightgown, baseball-glove, water-heater, cauliflower, cover, garbage-truck, forklift, bath-mat, chopping-board, computer-keyboard, propeller, wristband, gift-wrap, duck, railcar-(part-of-a-train), violin, football-helmet, blueberry, chopstick, piano, starfish, lawn-mower, fork, diaper, frying-pan, shark, wallet, duct-tape, pineapple, elk, toaster, earplug, wall-clock, cab-(taxi), zebra, bow-tie, hog, mallet, boiled-egg, knitting-needle, keycard, condiment, dragonfly, garlic, pepper-mill, drumstick, snowman, thumbtack, gasmask, pouch, teapot, sling-(bandage), barrow, bulldozer, spear, bookmark, mat-(gym-equipment), coffee-table, sleeping-bag, bat-(animal), runner-(carpet), iron-(for-clothing), bath-towel, coatrack, musical-instrument, bulletin-board, pie, tinfoil, overalls-(clothing), bib, pelican, egg, mascot, cistern, bookcase, giraffe, pad, trench-coat, bandage, chalice, flannel, doustpan, celery, sweet-potato, headset, bread-bin, bowler-hat, walking-stick, saddle-blanket, phonebook, seahorse, clasp, lollipop, desk, broccoli, nailfile, anklet, dress-suit, rag-doll, beanbag, gondola-(boat), bear, mushroom, cider, dishwasher, alcohol, clementine, flap, rifle, icecream, ski, snowboard, vacuum-cleaner, automatic-washer, trailer-truck, hamper, television-camera, cigar-box, tobacco-pipe, bouquet, candy-bar, ferry, bead, banjo, ladybug, pacifier, shovel, control, fishing-rod, cruise-ship, washbasin, whipped-cream, pen, goggles, pan-(metal-container), cucumber, nightshirt, dolphin, water-cooler, cloak, mop, pendulum, canoe, artichoke, heater, hammock, water-gun, almond, paintbrush, shredder-(for-paper), pita-(bread), liquor, eggbeater, scale-(measuring-instrument), dresser, ski-boot, cigarette-case, teakettle, armband, frog, file-cabinet, tow-truck, squid-(food), mouse-(computer-equipment), keg, tongs, deadbolt, quesadilla, hair-curler, koala, asparagus, platter, bobbin, coaster, milk, inhaler, salami, flamingo, life-jacket, coffeeepot, urinal, eggplant, business-card, mattress, fig-(fruit), hammer, nightshirt, cabana, suit-(clothing), kitchen-table, corset, gorilla, cocoa-(beverage), yacht, salmon-(fish), spice-rack, parachute, coil, squirrel, ironing-board, projectile-(weapon), coverall, trophy-cup, thread, measuring-stick, dinghy, crowbar, ski-pole, trunk, salad, dartboard, bedpan, award, rabbit, cincture, parka, colander, windsock, home-plate-(baseball), baboon, green-onion, éclair, toothpaste, saucer, highchair, handkerchief, pajamas, saxophone, potholder, ladle, spatula, first-aid-kit, veil, parakeet, scrubbing-brush, clip, blender, stapler-(stapling-machine), parrot, measuring-cup, owl, ice-maker, sweat-pants, videotape, corkscrew, marker, muffin, tiara, cast, beret, gun, tape-measure, generator, cowbell, sushi, hookah, seabird, crow, tachometer, cream-pitcher, battery, alligator, spider, Band-Aid, lightning-rod, hamburger, elevator-car, checkbook, hockey-stick, syringe, beeper, gelatin, wrench, water-scooter, hornet, fire-hose, Lego, stove, key, palette, chicken-(animal), deck-chair, fishing-rod, chaise-longue, hairbrush, flashlight, smoothie, mitten, flute-glass, crab-(animal), bagpipe, clothespin, soap, lizard, river-boat, boom-microphone, radish, paperweight, fire-engine, candy-cane, bow-(weapon), sponge, wedding-cake, hourglass, ice-pack, tea-bag, cappuccino, eagle, machine-gun, salmon-(food), wet-suit, clutch-bag, cube, brussels-sprouts, wolf, toothpick, kennel, soccer-ball, prawn, hamster, identity-card, egg-yolk, pegboard, honey, duckling, pencil, ham, saddle-(on-an-animal), gameboard, hot-sauce, amplifier, alarm-clock, tortilla, manatee, brownie, nutcracker, popsicle, funnel, hotplate, transpiline, crib, heron, shampoo, butter, army-tank, date-(fruit), bottle-opener, comet, camera-lens, jelly-bean, griddle, atomizer, armchair, bass-horn, hummingbird, salsa, baguet, sweatband, arctic-(type-of-shoe), footstool, power-shovel, drone, tractor-(farm-equipment), bunk-bed, food-processor, radio-receiver, cufflink, scarecrow, cock, cougar, chocolate-cake, wok, raspberry, ping-pong-ball, blackberry, dollhouse, space-shuttle, skewer, bobby-pin, school-bus, puffin, car-battery, razorblade, stirrup, drill, truffle-(chocolate), fighter-jet, thermometer, cupboard, screwdriver, sled, eel, pipe-bowl, broach, plume, sofa-bed, ferret, turtle, escargot, crescent-roll, printer, quilt, chocolate-bar, paddle, toaster-oven, motor-vehicle, puffer-(fish), soya-milk, cork-(bottle-plug), cabin-car, walrus, patty-(food), police-cruiser, skullcap, baseball, handsaw, Sharpie, stegococh, cape, receipt, notebook, rib-(food), paperback-book, perfume, ballet-skirt, stirrer, steak-(food), telephoto-lens, barbell, record-player, mound-(baseball), dental-floss, sparkler-(fireworks), microscope, strainer, wooden-leg, dish, peeler-(tool-for-fruit-and-vegetables), hammer, milkshake, detergent, octopus-(food), limousine, chessboard, Tabasco-sauce, curling-iron, convertible-(automobile), underdrawers, freight-car, dalmatian, notepad, seaplane, burrito, dishrag, packet, birthday-cake, binder, wooden-spoon, pool-table, sewing-machine, pitchfork, cardigan, crayon, manger, kettle, CD-player, barge, flash, rolling-pin, cleansing-agent, dagger, waffle, hardback-book, toast-(food), puppy, egg-roll, chili-(vegetable), kitchen-sink, chocolate-mousse, router-(computer-equipment), pencil-sharpener, pin-(non-jewelry), kayak, sharpener, grater, nut, shoulder-bag, pantyhose, plow-(farm-equipment), mint-candy, crisp-(potato-chip), needle, pea-(food), beef-(food), sherbert, pepper, iPod, bullet-train, polar-bear, headboard, volleyball, bulldog, crape, reamer-(juicer), birdfeeder, table-lamp, pocketknife, jewelry, meatball, pudding, hand-glass, Bible, money, stylus, sugarcane-(plant), cayenne-(spice), shepherd-dog, lip-balm, soup-bowl, cornbread

Table A4. Full list of the target categories present in the walking awareness dataset, sorted by the number of occurrences in the dataset.

| | | | |
|-----|--|---|-----|
| 221 | viduals with visual impairments to lead more independent | greatly improve the quality of life for visually impaired | 228 |
| 222 | and fulfilling lives. Our commitment to this cause remains | individuals. By introducing the WalkVLM model and the | 229 |
| 223 | unwavering, and we look forward to the next steps in this | accompanying walking awareness dataset, we are taking a | 230 |
| 224 | journey! | substantial step towards enhancing the independence and | 231 |
| | | safety of blind individuals as they navigate through their | 232 |
| 225 | E. Societal Impact | daily environments. | 233 |
| 226 | Our contribution extends beyond the realm of technological | Firstly, the WalkVLM model and dataset address a critical | 234 |
| 227 | advancement, offering significant societal benefits that can | need for more accessible and effective assistive technologies | 235 |

| Application Scenario | Models | Input Prompt |
|---|--|--|
| Normalize the annotation results | Llama 3.1 | <p>Please normalize the following manually annotated output to reduce information redundancy and maintain as standardized an output as possible. During the processing, please follow these guidelines:</p> <p>a. Convert all labels to lowercase.</p> <p>b. Remove any superfluous spaces or special characters.</p> <p>c. Retain the accurate position of objects in the sentence, such as what time or how many steps away.</p> <p>d. For similar or repetitive semantic annotations, reduce the redundancy of semantics.</p> <p>e. Output the result directly.</p> <p>The annotated text is as follows:</p> <p>...</p> |
| Instruct VLM to provide guidance on blind walking based on the provided video | DeepSeek (1.3B&7B) Yi-VL (6B) MiniCPM-V2.6 (8B) GPT-4o Qwen2-VL (7B) | <p>"request": "format the sentence below into the format, given in English",</p> <p>"restriction": "answer in json like the format given below without code block",</p> <p>"sentence": "Analyze the following video frames and determine the danger level for a blind person if they were to walk straight ahead. The danger levels are categorized as follows:: Low (open areas, with few people or obstacles): Mid (moderate danger, such as areas with some obstacles or moderate activity): High (high danger, such as narrow pathways, crowded areas, or busy roads)are the danger levels for the first two frames:1:{history_states[0]}2:history_states[1]} on this information and the provided image below, please provide the danger level for Frame 3.that danger level are indicated by single letters only. (A, B, or C)., provide walking instructions based on the provided image to ensure safe navigation.",</p> <p>"format": { "data": { "Frame 3 Danger Level": "string (A, B, or C)", "Walking Guidance": "string" } }</p> <p>...</p> |
| Training and inference of WalkVLM | WalkVLM | <p>"request": "format the sentence below into the format, given in English",</p> <p>"restriction": "answer in json like the format given below without code block",</p> <p>"sentence": "You are now a guide. I can't see the path and will be walking solely based on your instructions. Each input frame displays the road information ahead. The main objects in each image are { json_str }. Please provide clear and unobstructed walking directions. Describe in order: 1. Location (e.g., corridor, restaurant, market, downtown, street, foot path, bicycle path), 2. Weather conditions (e.g., overcast sky, sunny, partly cloudy, indoor), 3. Traffic flow rating (e.g., low: 0-4 people/minute, medium: 4-10 people/minute, high: 10+ people/minute), 4. Describe the overall scene based on the input images and all the information from the above three points, 5. Please guide me on how to proceed based on the input images and all previous descriptions.",</p> <p>"format": { "data": { "1. Location": "string", "2. Weather conditions": "string", "3. Traffic flow rating": "string", "4. Describe the overall scene in the image": "string", "5. Instructions on how I should proceed": "string" } }</p> <p>...</p> |
| Use LMM to evaluate the similarity between generated results and ground truth | GPT4 | <p>Please act as an impartial judge and evaluate the quality of the responses provided by multiple assistants displayed below. You should choose the assistant that matches the GT answer. Your evaluation should consider factors such as the helpfulness, relevance, accuracy, depth, creativity, and level of detail of their responses. Avoid any positional biases and ensure that the order in which the responses were presented does not influence your decision. Do not favor certain names of the assistants. Be as objective as possible. The answer should be the most closest to the semantics of the GT result and have the most concise answer. After providing your explanation, strictly follow the following format to output your final verdict: if assistant A is better, output "[[A]]", if assistant B is better, output "[[B]]", and similar formats for other answers. Request you select a relatively optimal result and directly output the option.</p> <p>{GT}</p> <p>{}</p> <p>The Start of Assistant A's Answer</p> <p>{}</p> <p>The End of Assistant A's Answer</p> <p>The Start of Assistant B's Answer</p> <p>{}</p> <p>The End of Assistant B's Answer</p> <p>...</p> <p>The Start of Assistant G's Answer</p> <p>{}</p> <p>The End of Assistant G's Answer</p> |

Table A5. All prompts utilized in this paper.

236 for the visually impaired. Traditional navigation aids often
 237 fall short in providing the necessary real-time information
 238 and adaptability required for complex environments. Our
 239 model, with its advanced capabilities in understanding and
 240 interpreting walking-related data, can offer more precise and
 241 context-aware guidance, thereby reducing the risks associ-

ated with independent travel.

Moreover, the dataset we have compiled is a valuable
 resource that can foster further research and development in
 the field of assistive technologies. By making this dataset
 publicly available, we encourage collaboration and innova-
 tion among researchers, leading to the creation of even more

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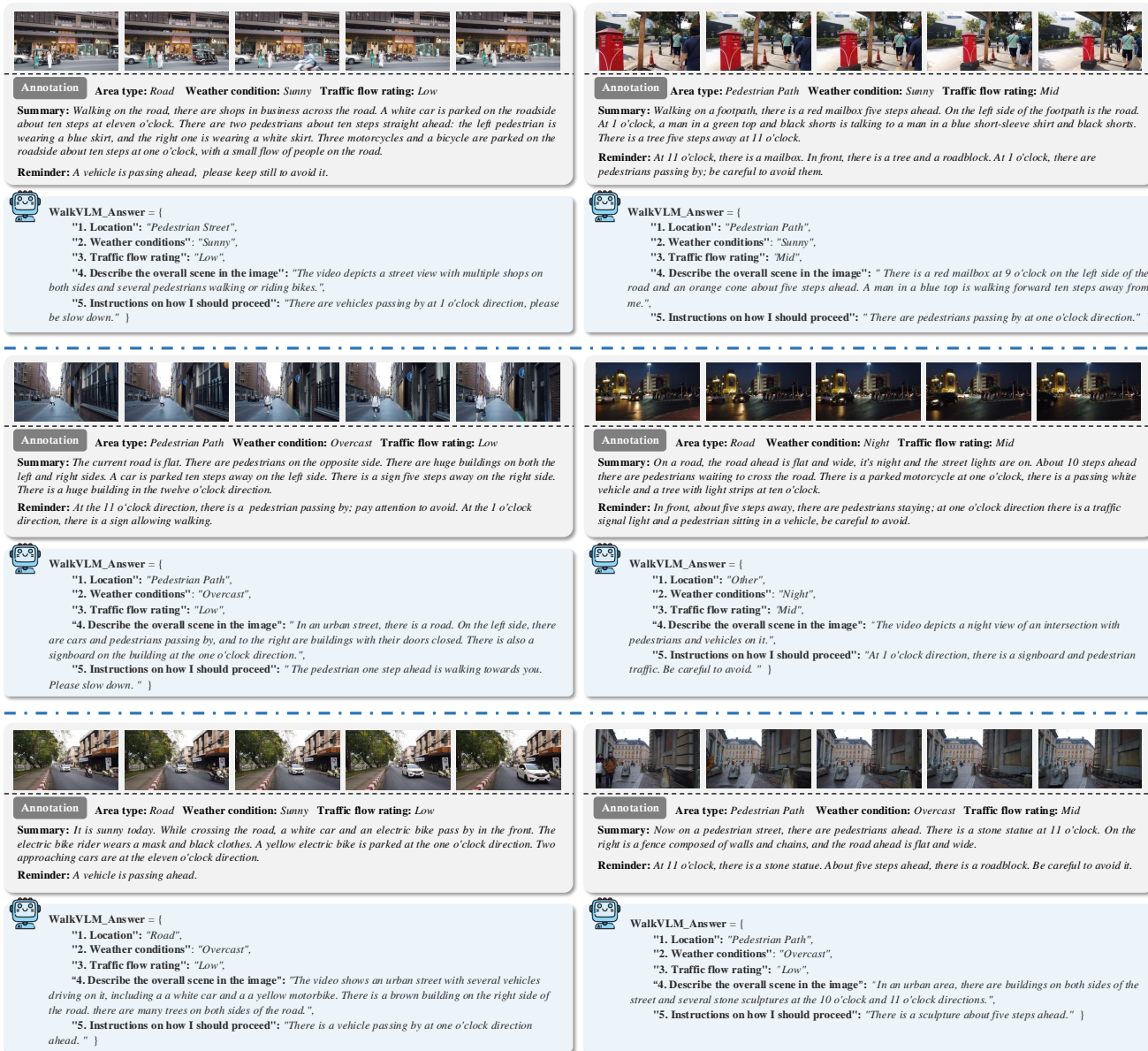


Figure A9. Hierarchical inference results visualization of WalkVLM.

248 sophisticated solutions that can cater to the diverse needs
249 of blind individuals. This collaborative effort can ultimately
250 result in technologies that are not only more effective but
251 also more widely adopted and accessible.

252 From an educational standpoint, our work can also play a
253 pivotal role in raising awareness about the challenges faced
254 by the visually impaired community. By showcasing the
255 potential of AI and machine learning in addressing these
256 challenges, we hope to inspire more individuals and organi-
257 zations to contribute towards creating a more inclusive soci-
258 ety. This increased awareness can lead to more supportive
259 policies and initiatives that focus on improving the quality

of life for the visually impaired.

260 Additionally, the WalkVLM model and dataset have the
261 potential to impact various industries beyond assistive tech-
262 nologies. For instance, they can be adapted for use in smart
263 city planning, where understanding pedestrian behavior and
264 safety is crucial. This broader application can lead to safer
265 and more accessible urban environments for everyone, not
266 just the visually impaired.

267 In summary, our contribution not only advances the state
268 of the art in AI and machine learning but also has far-reaching
269 societal implications. By providing a robust benchmark and
270 a rich dataset, we are paving the way for innovative solutions
271

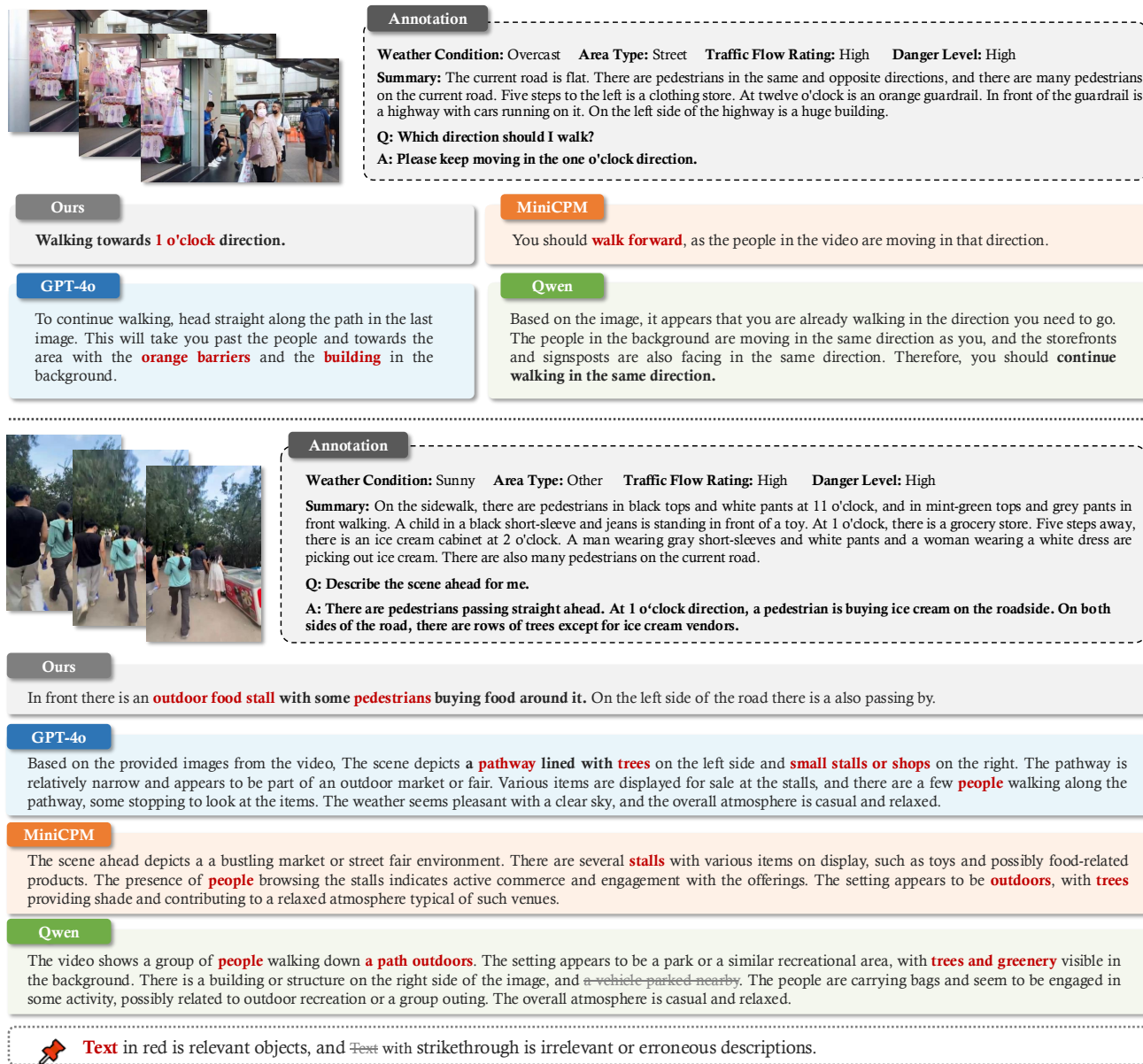


Figure A10. More QA visualization comparisons of different models.

272 that can significantly enhance the lives of blind individuals
273 and promote a more inclusive society.

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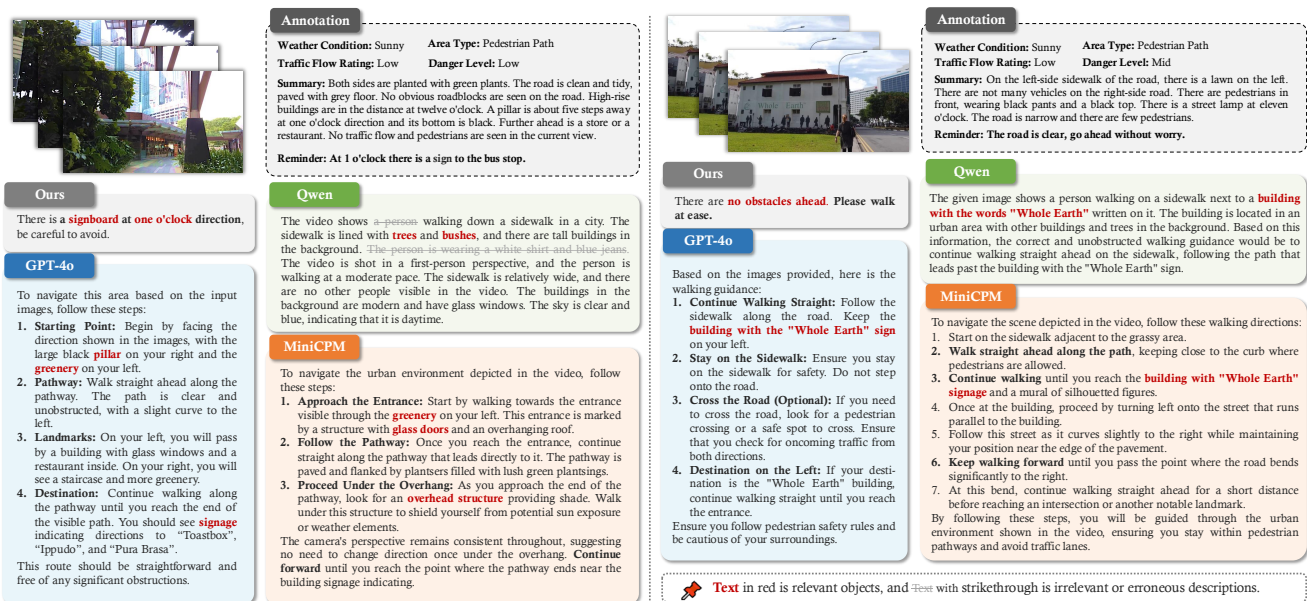


Figure A11. More reminder visualization comparisons of different models.

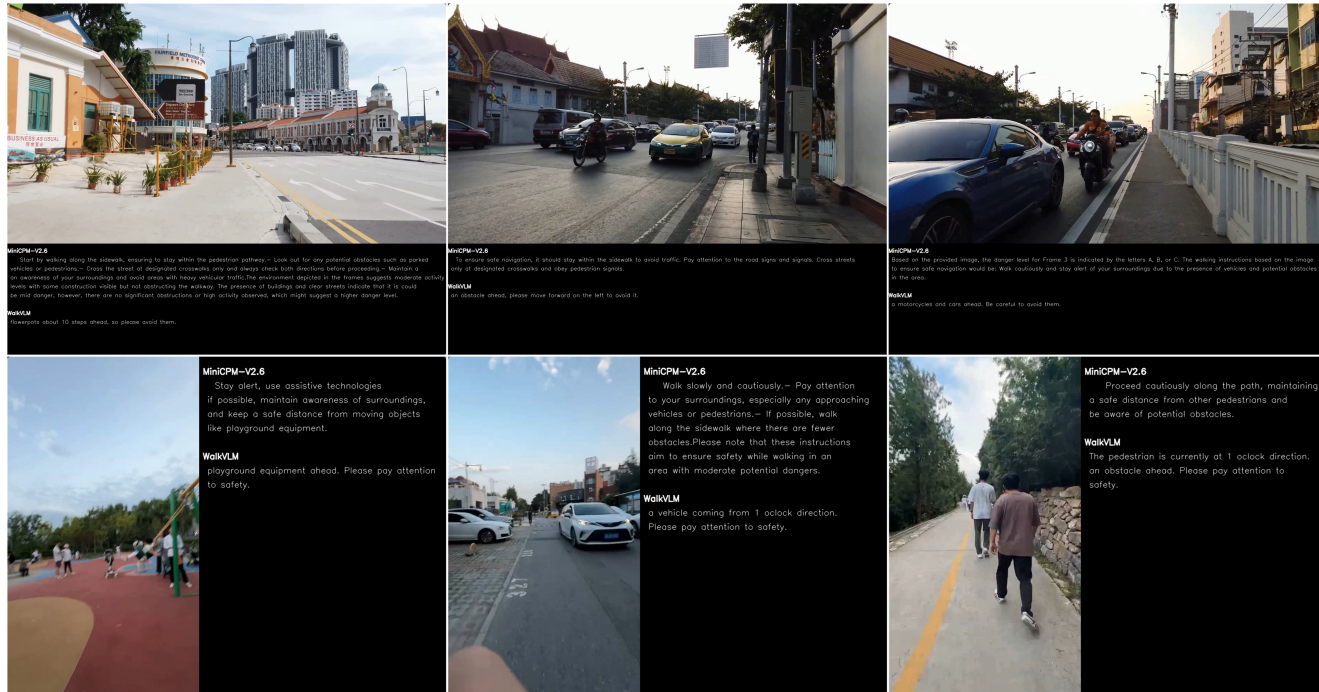


Figure A12. Sampling results of video stream inference in the blind walking task. Zoom in to view the generated results. See [here](#) for the video inference results. WalkVLM is capable of generating less temporal redundancy and providing more concise and informative responses.